Abstraction and Simulation



Simulation and Bisimulation

Dr. Liam O'Connor CSE, UNSW (for now) Term 1 2020

Abstraction and Simulation

Model Equivalence

Let A and B be Kripke structures.

Question

When does $A \models \varphi \Leftrightarrow B \models \varphi$ for all LTL formulae φ ?

Abstraction and Simulation

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Liam: prove it on the board

Abstraction and Simulation

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This is called *infinite completed trace equivalence*.

Abstraction and Simulation

Limitations of Traces



Traces cannot distinguish these two models!

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Model Equivalence

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hmm...

Is it (only) when A = B (graph isomorphism)?

Abstraction and Simulation

Model Equivalence

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When does
$$A \models \varphi \Leftrightarrow B \models \varphi$$
 for all CTL formulae φ ?

Is it (only) when A = B (graph isomorphism)?



Nope!

Tree Equivalence?

Is it (only) when the two automata have the same computation tree?

Abstraction and Simulation

Tree Equivalence?

Is it (only) when the two automata have the same computation tree?



Also no!

Definition

A (strong) *bisimulation* between two automata A and B is defined as a relation $\mathcal{R} \subseteq Q_A \times Q_B$ which satisfies:

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- If $s \mathcal{R} t$ and $s \xrightarrow{a} s'$ (with $a \in \Sigma_A, s' \in Q_A$) then there exists a $t' \in Q_B$ such that $t \xrightarrow{a} t'$ and $s' \mathcal{R} t'$.

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Result

For two finitely-branching automata A and B, $A \models \varphi \Leftrightarrow B \models \varphi$ for all CTL formulae φ iff they are *bisimilar*.

Abstraction and Simulation

Simulation



Abstraction and Simulation

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No, but one simulates the other.

Abstraction and Simulation

Simulation Relations

Definition

A *simulation* of an automaton *C* by an automaton *A* is defined as a relation $S \subseteq Q_C \times Q_A$ which satisfies:

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- If s S t and s → s' (with a ∈ Σ_C, s' ∈ Q_C) then there exists a t' ∈ Q_A such that t → t' and s' R t'.

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Abstraction and Traces

If
$$A \sqsubseteq C$$
, then every trace of C restricted to L_A is a trace of A .
 $\sigma_1 \sigma_2 \sigma_3 \cdots \in \operatorname{Traces}(C)$
 \Rightarrow
 $(\sigma_1 \cap L_A)(\sigma_2 \cap L_A)(\sigma_3 \cap L_A) \cdots \in \operatorname{Traces}(A)$

Let \mathcal{A} be a simulation relation, showing that $X \sqsubseteq Y$. Then for every run $\rho_1 \rho_2 \rho_3 \cdots \in Y$ is a run of X by applying the simulation relation as an *abstraction mapping*:

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Comparing Automata









What are the simulations between these?

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Reducing State Space

We want abstraction to shrink the state space for model checking. To do this, we need a guarantee that any property we prove about an abstraction applies just as well to the concrete model.

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Abstraction and Simulation

Universal CTL

Negation Normal Form

 φ is in negation normal form (NNF), written $\hat{\varphi}$, if all negations are applied only to atomic props. All formulae have a NNF equivalent.

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Example • AG*p* • AG AF*p* • EF*p* — Nope!

Abstraction and Simulation

Negation Normal Form

$$\neg \mathbf{AF}\varphi \equiv \mathbf{EG}\neg\varphi$$
$$\neg \mathbf{EF}\varphi \equiv \mathbf{AG}\neg\varphi$$
$$\neg \mathbf{AG}\varphi \equiv \mathbf{EF}\neg\varphi$$
$$\neg \mathbf{EG}\varphi \equiv \mathbf{AF}\neg\varphi$$
$$\neg \mathbf{AX}\varphi \equiv \mathbf{EX}\neg\varphi$$
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$$\neg \mathbf{E}(\varphi \cup \psi) \equiv$$

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$$\neg \mathbf{EX}\varphi \equiv \mathbf{EX}\neg\varphi$$

$$\neg \mathbf{E}(\varphi \cup \psi) \equiv \mathbf{A}(\neg\varphi \otimes \neg\psi)$$

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Release Operator

The temporal operator $\varphi \mathbf{R} \psi$ says that ψ will not become false unless φ happens first.

$$\sigma \models \varphi \ \mathbf{R} \ \psi \quad \Leftrightarrow \quad \forall n \ge 0. \ (\forall 0 \le k < n. \ \sigma|_k \not\models \varphi) \Rightarrow \sigma|_n \models \psi$$

A and E variants in CTL follow the usual pattern.

Bisimulation and simulation

Suppose that $A \sqsubseteq B$ and $B \sqsubseteq A$. Does that mean A is bisimilar to B?

Bisimulation and simulation

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Nope! This is another equivalence called *simulation equivalence*. Because of the abstraction result, ACTL is the logic that characterises simulation equivalence.

The Linear-time Branching-time Spectrum

Coarseness of Equivalences

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There are many, many more equivalences.

Rob van Glabbeek categorised all of these equivalences and more into the *linear-time branching-time spectrum*, which is a major focus of his course at this university, COMP6752.

Bibliography

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